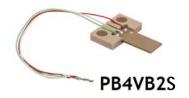


# Piezoelectric Bimorph with Holder, 150 V, ±135 µm Travel



## **Description**

The PB4VB2S bender actuator consists of a piezoelectric bimorph attached to a specially designed carrier which makes it easier for customers to incorporate. The holder has two  $\emptyset$ 4.3 mm thru holes with a 12.5 mm center-to-center spacing that accepts M3 or M4 cap screws. The piezoelectric bimorph is co-fired with multiple piezoelectric ceramic layers. The PB4VB2S offers a maximum displacement of  $\pm 135~\mu m \pm 15\%$ . It has three electrodes on the top surface and a silver plus sign is located next to the electrode attached to the red wire, which should receive positive bias.

# **Specifications**

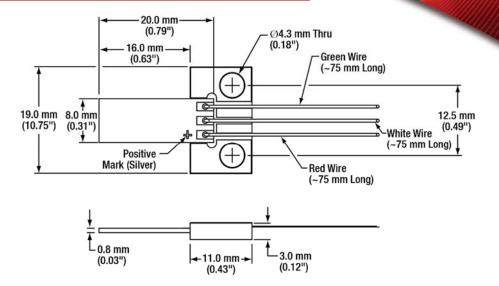
PB4VB2S <sup>a</sup>		
Drive Voltage Range	0 - 150 V	
Displacement at 150V	±135 μm ± 15%	
Hysteresis	<15% (See Graph on Next Page)	
Free Length	16 mm	
Piezo used Inside	PB4VB2W	
Blocking Force at 150V	1.4 N (0.31 lbs)	
Resonant Frequency <sup>b</sup>	930 Hz (No Load)	
Dissipation Factor <sup>c</sup>	<2.0%	
Capacitance <sup>c</sup>	145 nF ± 15% for Each Side of the Bimorph	
Operating Temperature	-25 to 130 °C	
Curie Temperature	230 °C	
External Electrodes	Screen-Printed Silver	
	Length: 20.0 mm ± 0.5 mm	
Bare Piezo Dimensions	Width: $8.0 \text{ mm} \pm 0.1 \text{mm}$	
	Thickness: 0.8 mm ± 0.1 mm	
	Length: $11.0 \text{ mm} \pm 0.2 \text{ mm}$	
Holder Dimensions	Width: 19.0 mm ± 0.2 mm	
	Thickness: 3.0 mm ± 0.1 mm	



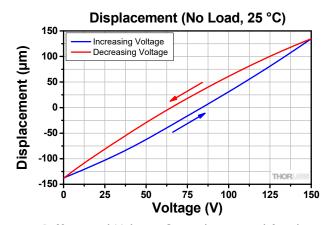
- a. All specifications are quoted at 25 °C, unless otherwise stated.
- b. Fixed on breadboard, without load.
- c. Specified at 1 kHz, 1 V<sub>RMS</sub>.



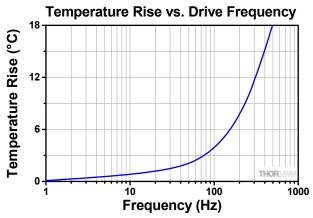
## **Drawing**



# Typical Performance Plots



Differential Voltage Control was used for this displacement test: Red Wire at 150 V, White Wire varied from 0 to 150 V, Green Wire at 0 V.

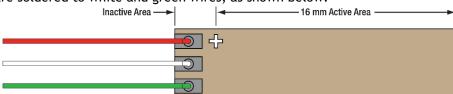


These temperature rises were measured after applying a sine-wave drive voltage ranging from 0 to 150 V applied to the white wire at the specified frequency for 10 minutes. The red wire was held at 150 V and the green wire at 0 V.

# **Operations**

#### **Electrical Connection**

The PB4VB2S has three electrodes: the positive electrode is attached to a red wire, and the other two electrodes are soldered to white and green wires, as shown below.





**Caution:** After driving, the piezo is fully charged. Directly connecting the green and white wires or red and white wires has the risk of electricity discharging, spark, and even failure. We recommend using a resistor (>1 k $\Omega$ ) between the wires to release the charge.

### **Driving Modes**

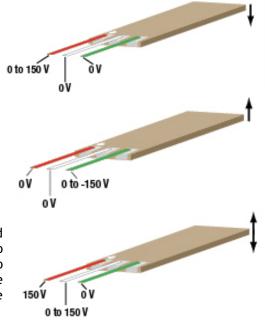
The bimorph bender can be operated following one of two basic driving principles:

## Single-Side Voltage Control

If a positive voltage ( $\leq 150$  V) is applied between the red and white lead wires, PB4VB2W will bend down when the silver plus is facing up, as shown in the diagrams below.

If a negative voltage (≥-150 V) is applied between the white and green lead wires, PB4VB2W will bend up when the silver plus is facing up, as shown in the diagrams below.

When operating in Single-Side Voltage Control mode, never apply the voltage to both the green and red leads at the same time, as a voltage difference >150 V between the two leads could damage the actuator.



## Differential Voltage Control

In this mode, the bending can be controlled both upwards and downwards. This type of the driving requires a dual power supply to provide differential voltage to the two electrodes which are attached to the red and green wires, respectively. Then the voltage applied to the white wire can be varied to obtain up and down, as shown in the tale below.

Soldering Contact	Red	White	Green
Option 1	150 V	0 V to 150 V	GND
Option 2	75 V	-75 V to 75V	-75 V

#### Long Term Operation

PBAVB2W actuators remained function after a long-term durability test of 1x108 cycles at a frequency of 100 Hz under conditions of 25 °C room temperature and 45% ambient humidity.

## **Storage Instruction**

- Do not store the device at temperature above 80 °C.
- Do not store the device in humid environments. The relative humidity (RH) should be less than 40%.
- Do not immerse the device in organic solvents.
- Do not use the device around combustible gases or liquids.